



4004 SINGLE CHIP 4-BIT P-CHANNEL MICROPROCESSOR

- 4-Bit Parallel CPU With 46 Instructions
- Instruction Set Includes Conditional Branching, Jump to Subroutine and Indirect Fetching
- Binary and Decimal Arithmetic Modes
- 10.8 Microsecond Instruction Cycle

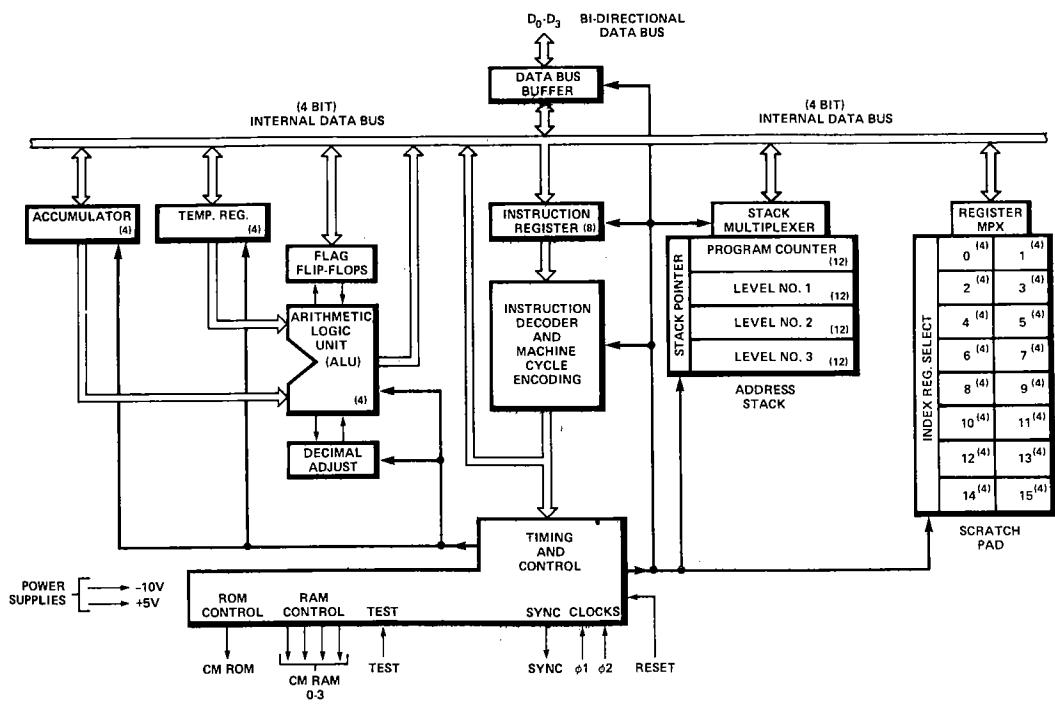
- CPU Directly Compatible With MCS-40 ROMs and RAMs
- Easy Expansion – One CPU can Directly Drive up to 32,768 Bits of ROM and up to 5120 Bits of RAM
- Standard Operating Temperature Range of 0° to 70°C
- Also Available With -40° to +85°C Operating Range

The Intel® 4004 is a complete 4-bit parallel central processing unit (CPU). The 4004 easily interfaces with keyboards, switches, displays, A-D converters, printers and other peripheral equipment.

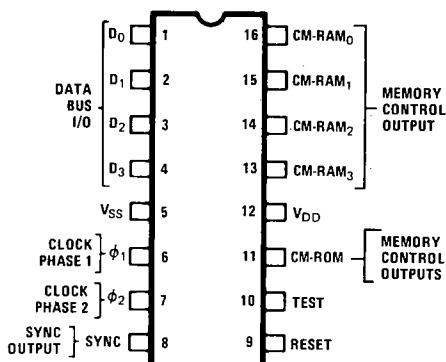
The CPU can directly address 4K 8-bit instruction words of program memory and 5120 bits of data storage RAM. Sixteen index registers are provided for temporary data storage. Up to 16 4-bit input ports and 16 4-bit output ports may also be directly addressed.

The 4004 is fabricated with P-channel silicon gate MOS technology.

MCS-4/40



Pin Description



D₀-D₃

BIDIRECTIONAL DATA BUS. All address and data communication between the processor and the RAM and ROM chips occurs on these 4 lines.

RESET

RESET input. A logic "1" level at this input clears all flags and status registers and forces the program counter to zero. To completely clear all address and index registers, RESET must be applied for 64 clock cycles (8 machine cycles).

TEST

TEST input. The logical state of this signal may be tested with the JCN instruction.

SYNC

SYNC output. Synchronization signal generated by the processor and set to the ROM and RAM chips. It indicates the beginning of an instruction cycle.

CM-ROM

CM-ROM output. This is the ROM selection signal sent out by the processor when data is required from program memory.

CM-RAM₀ – CM-RAM₃

CM-RAM outputs. These are the bank selection signals for the 4002 RAM chips in the system.

ϕ_1 , ϕ_2

Two phase clock inputs.

V_{SS}

Most negative voltage.

V_{DD}

V_{SS} -15 ±5% main supply voltage.

Instruction Set Format

A. Machine Instructions

- 1 word instruction – 8-bits requiring 8 clock periods (instruction cycle).
- 2 word instruction – 16-bits requiring 16 clock periods (2 instruction cycles).

Each instruction is divided into two four-bit fields. The upper 4-bits is the OPR field containing the operation code. The lower 4-bits is the OPA field containing the modifier. For two word instructions, the second word contains address information or data.

The upper 4-bits (OPR) will always be fetched before the lower 4-bits (OPA) during M_1 and M_2 times respectively.

ONE WORD INSTRUCTIONS								TWO WORD INSTRUCTIONS							
1st INSTRUCTION CYCLE								2nd INSTRUCTION CYCLE							
D ₃ D ₂ D ₁ D ₀ D ₃ D ₂ D ₁ D ₀								D ₃ D ₂ D ₁ D ₀ D ₃ D ₂ D ₁ D ₀							
OPR OPA								OPR OPA							
OP CODE MODIFIER								OP CODE MODIFIER							
X X X X X X X X								X X X X X X X X							
INDEX REGISTER ADDRESS R R R R								A ₃ A ₃ A ₃ A ₃							
OR								X X X X C ₁ C ₂ C ₃ C ₄							
INDEX REGISTER PAIR R R R X								A ₂ A ₂ A ₂ A ₂							
OR								A ₁ A ₁ A ₁ A ₁							
X X X X D D D D								DATA							
INDEX REGISTER ADDRESS R R R R								A ₂ A ₂ A ₂ A ₂							
OR								A ₁ A ₁ A ₁ A ₁							
X X X X D D D D								INDEX REGISTER PAIR R R X							
INDEX REGISTER ADDRESS R R R R								A ₂ A ₂ A ₂ A ₂							
OR								A ₁ A ₁ A ₁ A ₁							
X X X X D D D D								DATA							

Table I. Machine Instruction Format

B. Input/Output and RAM Instructions and Accumulator Group Instructions

In these instructions (which are all single word) the OPR contains a 4-bit code which identifies either the I/O instruction or the accumulator group instruction and the OPA contains a 4-bit code which identifies the operation to be performed. Table II illustrates the contents of each 4-bit field.

D ₃ D ₂ D ₁ D ₀ D ₃ D ₂ D ₁ D ₀
OPR OPA
1 1 1 0 X X X X
INPUT/OUTPUT & RAM INSTRUCTIONS

1 1 1 1 X X X X
ACCUMULATOR GROUP INSTRUCTIONS

WHERE X = EITHER A "0" OR A "1".

Table II. I/O and Accumulator Group Instruction Formats

4004 Instruction Set

BASIC INSTRUCTIONS (* = 2 Word Instructions)

Hex Code	Mnemonic	OPR				OPA				DESCRIPTION OF OPERATION
		D ₃	D ₂	D ₁	D ₀	D ₃	D ₂	D ₁	D ₀	
00	NOP	0	0	0	0	0	0	0	0	No operation.
1 -	*JCN	0	0	0	1	C ₁	C ₂	C ₃	C ₄	Jump to ROM address A ₂ A ₂ A ₂ A ₂ , A ₁ A ₁ A ₁ A ₁ (within the same ROM that contains this JCN instruction) if condition C ₁ C ₂ C ₃ C ₄ is true, otherwise go to the next instruction in sequence.
--		A ₂	A ₂	A ₂	A ₂	A ₁	A ₁	A ₁	A ₁	
2 -	*FIM	0	0	1	0	R	R	R	0	Fetch immediate (direct) from ROM Data D ₂ D ₂ D ₂ D ₂ D ₁ D ₁ D ₁ to index register pair location RRR.
--		D ₂	D ₂	D ₂	D ₂	D ₁	D ₁	D ₁	D ₁	
3 -	FIN	0	0	1	1	R	R	R	0	Fetch indirect from ROM. Send contents of index register pair location 0 out as an address. Data fetched is placed into register pair location RRR.
3 -	JIN	0	0	1	1	R	R	R	1	Jump indirect. Send contents of register pair RRR out as an address at A ₁ and A ₂ time in the instruction cycle.
4 -	*JUN	0	1	0	0	A ₃	A ₃	A ₃	A ₃	Jump unconditional to ROM address A ₃ A ₃ A ₃ A ₃ A ₂ A ₂ A ₂ A ₂ A ₁ A ₁ A ₁ A ₁ .
--		A ₂	A ₂	A ₂	A ₂	A ₁	A ₁	A ₁	A ₁	
5 -	*JMS	0	1	0	1	A ₃	A ₃	A ₃	A ₃	Jump to subroutine ROM address A ₃ A ₃ A ₃ A ₃ A ₂ A ₂ A ₂ A ₂ A ₁ A ₁ A ₁ A ₁ , save old address (up 1 level in stack.)
--		A ₂	A ₂	A ₂	A ₂	A ₁	A ₁	A ₁	A ₁	
6 -	INC	0	1	1	0	R	R	R	R	Increment contents of register RRRR.
7 -	*ISZ	0	1	1	1	R	R	R	R	Increment contents of register RRRR. Go to ROM address A ₂ A ₂ A ₂ A ₂ A ₁ A ₁ A ₁ A ₁ (within the same ROM that contains this ISZ instruction) if result ≠ 0, otherwise go to the next instruction in sequence.
--		A ₂	A ₂	A ₂	A ₂	A ₁	A ₁	A ₁	A ₁	
8 -	ADD	1	0	0	0	R	R	R	R	Add contents of register RRRR to accumulator with carry.
9 -	SUB	1	0	0	1	R	R	R	R	Subtract contents of register RRRR to accumulator with borrow.
A -	LD	1	0	1	0	R	R	R	R	Load contents of register RRRR to accumulator.
B -	XCH	1	0	1	1	R	R	R	R	Exchange contents of index register RRRR and accumulator.
C -	BBL	1	1	0	0	D	D	D	D	Branch back (down 1 level in stack) and load data DDDD to accumulator.
D -	LDM	1	1	0	1	D	D	D	D	Load data DDDD to accumulator.
F0	CLB	1	1	1	1	0	0	0	0	Clear both. (Accumulator and carry)
F1	CLC	1	1	1	1	0	0	0	1	Clear carry.
F2	IAC	1	1	1	1	0	0	1	0	Increment accumulator.
F3	CMC	1	1	1	1	0	0	1	1	Complement carry.
F4	CMA	1	1	1	1	0	1	0	0	Complement accumulator.
F5	RAL	1	1	1	1	0	1	0	1	Rotate left. (Accumulator and carry)
F6	RAR	1	1	1	1	0	1	1	0	Rotate right. (Accumulator and carry)
F7	TCC	1	1	1	1	0	1	1	1	Transmit carry to accumulator and clear carry.
F8	DAC	1	1	1	1	1	0	0	0	Decrement accumulator.
F9	TCS	1	1	1	1	1	0	0	1	Transfer carry subtract and clear carry.
FA	STC	1	1	1	1	1	0	1	0	Set carry.
FB	DAA	1	1	1	1	1	0	1	1	Decimal adjust accumulator.
FC	KBP	1	1	1	1	1	1	0	0	Keyboard process. Converts the contents of the accumulator from a one out of four code to a binary code.
FD	DCL	1	1	1	1	1	1	0	1	Designate command line.

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4001/4002/4008/4009/4289 INPUT/OUTPUT AND RAM INSTRUCTIONS

Hex Code	Mnemonic	OPR			OPA		DESCRIPTION OF OPERATION
		D ₃	D ₂	D ₁	D ₃	D ₂	
2 -	SRC	0	0	1	0	R	Send register control. Send the address (contents of index register pair RRR) to ROM and RAM at X ₂ and X ₃ time in the instruction cycle.
E0	WRM	1	1	1	0	0	Write the contents of the accumulator into the previously selected RAM main memory character.
E1	WMP	1	1	1	0	0	Write the contents of the accumulator into the previously selected RAM output port. (Output Lines)
E2	WRR	1	1	1	0	0	Write the contents of the accumulator into the previously selected ROM output port. (I/O Lines)
E3	WPM	1	1	1	0	0	Write the contents of the accumulator into the previously selected half byte of read/write program memory (used with 4008/4009 or 4289 only)
E4	WR0	1	1	1	0	0	Write the contents of the accumulator into the previously selected RAM status character 0.
E5	WR1	1	1	1	0	0	Write the contents of the accumulator into the previously selected RAM status character 1.
E6	WR2	1	1	1	0	0	Write the contents of the accumulator into the previously selected RAM status character 2.
E7	WR3	1	1	1	0	0	Write the contents of the accumulator into the previously selected RAM status character 3.
E8	SBM	1	1	1	0	1	Subtract the previously selected RAM main memory character from accumulator with borrow.
E9	RDM	1	1	1	0	1	Read the previously selected RAM main memory character into the accumulator.
EA	RDR	1	1	1	0	1	Read the contents of the previously selected ROM input port into the accumulator. (I/O Lines)
EB	ADM	1	1	1	0	1	Add the previously selected RAM main memory character to accumulator with carry.
EC	RD0	1	1	1	0	1	Read the previously selected RAM status character 0 into accumulator.
ED	RD1	1	1	1	0	1	Read the previously selected RAM status character 1 into accumulator.
EE	RD2	1	1	1	0	1	Read the previously selected RAM status character 2 into accumulator.
EF	RD3	1	1	1	0	1	Read the previously selected RAM status character 3 into accumulator.

MCS 440

4004 Instruction Codes

Hex	Mnemonic	Hex	Mnemonic	Hex	Mnemonic	Hex	Mnemonic
00	-	40	JUN	80	ADD 0	C0	BBL 0
01	-	41	JUN	81	ADD 1	C1	BBL 1
02	-	42	JUN	82	ADD 2	C2	BBL 2
03	-	43	JUN	83	ADD 3	C3	BBL 3
04	-	44	JUN	84	ADD 4	C4	BBL 4
05	-	45	JUN	85	ADD 5	C5	BBL 5
06	-	46	JUN	86	ADD 6	C6	BBL 6
07	-	47	JUN	87	ADD 7	C7	BBL 7
08	-	48	JUN	88	ADD 8	C8	BBL 8
09	-	49	JUN	89	ADD 9	C9	BBL 9
0A	-	4A	JUN	8A	ADD 10	CA	BBL 10
0B	-	4B	JUN	8B	ADD 11	CB	BBL 11
0C	-	4C	JUN	8C	ADD 12	CC	BBL 12
0D	-	4D	JUN	8D	ADD 13	CD	BBL 13
0E	-	4E	JUN	8E	ADD 14	CE	BBL 14
0F	-	4F	JUN	8F	ADD 15	CF	BBL 15
10	JCN	CN=0	50	JMS	Second hex digit is part of jump address.	90	SUB 0
11	JCN	CN=1 also JNT	51	JMS		91	SUB 1
12	JCN	CN=2 also JC	52	JMS		92	SUB 2
13	JCN	CN=3	53	JMS		93	SUB 3
14	JCN	CN=4 also JZ	54	JMS		94	SUB 4
15	JCN	CN=5	55	JMS		95	SUB 5
16	JCN	CN=6	56	JMS		96	SUB 6
17	JCN	CN=7	57	JMS		97	SUB 7
18	JCN	CN=8	58	JMS		98	SUB 8
19	JCN	CN=9 also JT	59	JMS		99	SUB 9
1A	JCN	CN=10 also JNC	5A	JMS		9A	SUB 10
1B	JCN	CN=11	5B	JMS		9B	SUB 11
1C	JCN	CN=12 also JNZ	5C	JMS		9C	SUB 12
1D	JCN	CN=13	5D	JMS		9D	SUB 13
1E	JCN	CN=14	5E	JMS		9E	SUB 14
1F	JCN	CN=15	5F	JMS		9F	SUB 15
20	FIM	0	60	INC 0		A0	LD 0
21	SRC	0	61	INC 1		A1	LD 1
22	FIM	2	62	INC 2		A2	LD 2
23	SRC	2	63	INC 3		A3	LD 3
24	FIM	4	64	INC 4		A4	LD 4
25	SRC	4	65	INC 5		A5	LD 5
26	FIM	6	66	INC 6		A6	LD 6
27	SRC	6	67	INC 7		A7	LD 7
28	FIM	8	68	INC 8		A8	LD 8
29	SRC	8	69	INC 9		A9	LD 9
2A	FIM	10	6A	INC 10		AA	LD 10
2B	SRC	10	6B	INC 11		AB	LD 11
2C	FIM	12	6C	INC 12		AC	LD 12
2D	SRC	12	6D	INC 13		AD	LD 13
2E	FIM	14	6E	INC 14		AE	LD 14
2F	SRC	14	6F	INC 15		AF	LD 15
30	FIN	0	70	ISZ 0		80	XCH 0
31	JIN	0	71	ISZ 1		81	XCH 1
32	FIN	2	72	ISZ 2		82	XCH 2
33	JIN	2	73	ISZ 3		83	XCH 3
34	FIN	4	74	ISZ 4		84	XCH 4
35	JIN	4	75	ISZ 5		85	XCH 5
36	FIN	6	76	ISZ 6		86	XCH 6
37	JIN	6	77	ISZ 7		87	XCH 7
38	FIN	8	78	ISZ 8		88	XCH 8
39	JIN	8	79	ISZ 9		89	XCH 9
3A	FIN	10	7A	ISZ 10		BA	XCH 10
3B	JIN	10	7B	ISZ 11		BB	XCH 11
3C	FIN	12	7C	ISZ 12		BC	XCH 12
3D	JIN	12	7D	ISZ 13		BD	XCH 13
3E	FIN	14	7E	ISZ 14		BE	XCH 14
3F	JIN	14	7F	ISZ 15		BF	XCH 15

Absolute Maximum Ratings*

Ambient Temperature Under Bias	0°C to 70°C
Storage Temperature	-55°C to + 125°C
Input Voltages and Supply Voltage with respect to V _{SS}	+0.5V to -20V
Power Dissipation	1.0 Watt

***COMMENT:**
Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

D.C. and Operating Characteristics

$T_A = 0^\circ\text{C}$ to 70°C ; $V_{SS} - V_{DD} = 15\text{V} \pm 5\%$; $t_{\phi PW} = t_{\phi D1} = 400$ nsec; logic "0" is defined as the more positive voltage (V_{IH} , V_{OH}); logic "1" is defined as the more negative voltage (V_{IL} , V_{OL}); Unless Otherwise Specified.

SUPPLY CURRENT

Symbol	Parameter	Min.	Limit Typ.	Max.	Unit	Test Conditions
I_{DD}	Average Supply Current		30	40	mA	$T_A = 25^\circ\text{C}$

INPUT CHARACTERISTICS

I_{LI}	Input Leakage Current	10	μA	$V_{IL} = V_{DD}$	
V_{IH}	Input High Voltage (Except Clocks)	$V_{SS} - 1.5$	$V_{SS} + .3$	V	
V_{IL}	Input Low Voltage (Except Clocks)	V_{DD}	$V_{SS} - 5.5$	V	
V_{ILO}	Input Low Voltage	V_{DD}	$V_{SS} - 4.2$	V	4004 TEST Input
V_{IHC}	Input High Voltage Clocks	$V_{SS} - 1.5$	$V_{SS} + .3$	V	
V_{ILC}	Input Low Voltage Clocks	V_{DD}	$V_{SS} - 13.4$	V	

MCS 1/40

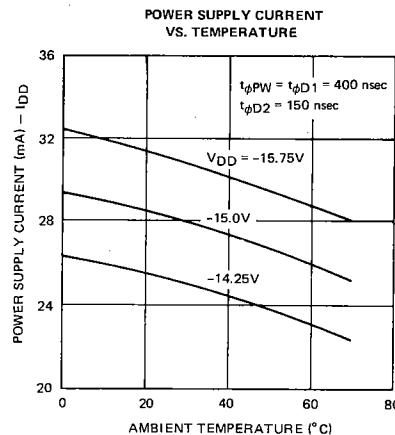
OUTPUT CHARACTERISTICS

I_{LO}	Data Bus Output Leakage Current	10	μA	$V_{OUT} = -12\text{V}$
V_{OH}	Output High Voltage	$V_{SS} - .5\text{V}$	V_{SS}	V
I_{OL}	Data Lines Sinking Current	8	15	mA
I_{OL}	CM-ROM Sinking Current	6.5	12	mA
I_{OL}	CM-RAM Sinking Current	2.5	6	mA
V_{OL}	Output Low Voltage, Data Bus, CM, SYNC	$V_{SS} - 12$	$V_{SS} - 6.5$	V
R_{OH}	Output Resistance, Data Line "0" Level	150	250	Ω
R_{OH}	CM-ROM Output Resistance, Data Line "0" Level	320	600	Ω
R_{OH}	CM-RAM Output Resistance, Data Line "0" Level	1.1	1.8	$\text{k}\Omega$

CAPACITANCE

C_{ϕ}	Clock Capacitance	14	20	pF	$V_{IN} = V_{SS}$
C_{DB}	Data Bus Capacitance	7	10	pF	$V_{IN} = V_{SS}$
C_{IN}	Input Capacitance		10	pF	$V_{IN} = V_{SS}$
C_{OUT}	Output Capacitance		10	pF	$V_{IN} = V_{SS}$

Typical D.C. Characteristics



A.C. Characteristics

 $T_A = 0^\circ\text{C}$ to 70°C , $V_{SS} - V_{DD} = 15\text{V} \pm 5\%$

MCS-40

Symbol	Parameter	Min.	Limit Typ.	Max.	Unit	Test Conditions
t_{CY}	Clock Period		1.35	2.0	μsec	
$t_{\phi R}$	Clock Rise Time			50	ns	
$t_{\phi F}$	Clock Fall Times			50	ns	
$t_{\phi PW}$	Clock Width	380	480		ns	
$t_{\phi D1}$	Clock Delay ϕ_1 to ϕ_2	400	550		ns	
$t_{\phi D2}$	Clock Delay ϕ_2 to ϕ_1	150			ns	
t_W	Data-In, CM, SYNC Write Time	350	100		ns	
$t_H^{[1,3]}$	Data-In, CM, SYNC Hold Time	40	20		ns	
$t_H^{[3]}$	Data Bus Hold Time During M_2 - X_1 and and X_2 - X_3 Transition.	150			ns	
$t_{OS}^{[2]}$	Set Time (Reference)	0			ns	
t_{ACC}	Data-Out Access Time Data Lines Data Lines SYNC CM-ROM CM-RAM			930 700 930 930 930	ns ns ns ns ns	$C_{OUT} = 500\text{pF}$ Data Lines 200pF Data Lines ^[4] 500pF SYNC 160pF CM-ROM 50pF CM-RAM
t_{OH}	Data-Out Hold Time	50	150		ns	$C_{OUT} = 20\text{pF}$

Notes: 1. t_H measured with $t_{\phi R} = 10\text{nsec}$.2. t_{ACC} is Data Bus, SYNC and CM-line output access time referred to the ϕ_2 trailing edge which clocks these lines out. t_{OS} is the same output access time referred to the leading edge of the next ϕ_2 clock pulse.3. All MCS-40 components which may transmit instruction or data to the 4004 at M_2 and X_2 always enter a float state until the 4004 takes over the data bus at X_1 and X_3 time. Therefore the t_H requirement is always insured since each component contributes $10\mu\text{A}$ of leakage current and 10pF of capacitance which guarantees that the data bus cannot change faster than $1\text{V}/\mu\text{s}$.4. $C_{DATA\ BUS} = 200\text{pF}$ if 4008 and 4009 or 4289 is used.

4004

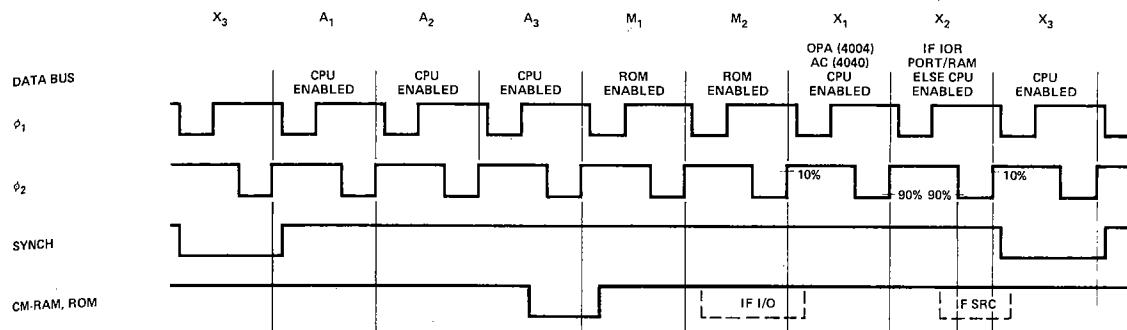


Figure 1. Timing Diagram.

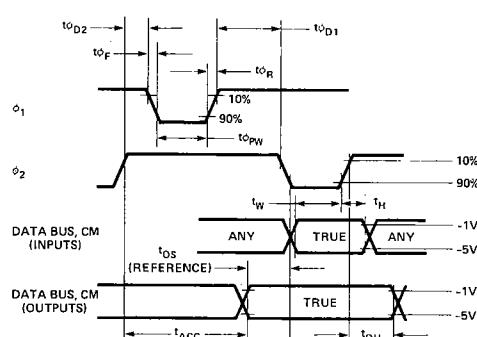


Figure 2. Timing Detail.